

Supersymmetric backgrounds

from Sd $N=1$ supergravity

@ Riemann Center for Geometry and Physics

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Tokyo institute of technology

Yosuke Imamura

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collaboration w/ Hiroki Matsuno

Introduction

Recent progress in SUSY gauge theories

→ Exact results

- Partition function, Indices
- Wilson loops, Polyakov loops
- Surface operators
- Domain walls

By using localization we can compute these quantities exactly.

(Supersymmetric) localization

$$Z = \int \mathcal{D}\Phi e^{-S_0[\Phi]}$$

$$(\mathcal{Q}S_0 = 0)$$

↓ \mathcal{Q} -exact deformation

$$Z_t(t) = \int \mathcal{D}\Phi e^{-S_0 - t\mathcal{Q}V}$$

$$\left(\begin{array}{l} t \in \mathbb{R}_+ \\ \mathcal{Q}^2 V = 0 \\ \mathcal{Q}V \geq 0 \end{array} \right)$$

This is independent of t .

We can perform the path integral in $t \rightarrow \infty$ limit.

Many results has been obtained for various background manifolds

3d and 4d examples

T^4 : Witten ('82) \Rightarrow Witten Index

S^4 : Pestun (0712.2824)

S^3 : Kapustin, Willett, Yankov (0909.4559)

⋮

These results are based on the realization of rigid supersymmetry \mathcal{Q} on curved backgrounds.

A systematic way of constructing SUSY theories on curved backgrounds using off-shell supergravity was proposed in Festuccia - Seiberg (1105.0689)

Weyl multiplet $(e_{\hat{\mu}\nu}, \psi_{\hat{\mu}\alpha}, \dots)$
 $\psi_{\hat{\mu}\alpha}$ \leftarrow gravitino

Rigid SUSY

$$\delta_{\alpha}(\xi) \psi_{\mu} \equiv D_{\mu} \xi + \dots = 0$$

$\delta_{\alpha}(\xi)$: local supersymmetry

Integrability condition \rightarrow SUSY backgrounds

Supersymmetric backgrounds in 4d and 3d

Klare-Tomasello-Zaffaroni (1205.1069)

Dumitrescu-Festuccia-Seiberg (1205.1115)

Dumitrescu-Festuccia (1209.5408)

Closset-Dumitrescu-Festuccia-Kamargodski (2013.1212)

Cassani-Klare-Martelli-Tomasello-Zaffaroni (1207.2181)

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We also had { Martelli's talk

Sparks' talk on Tuesday

These analyses showed that the constraints are not so strong.

There are infinitely many deformations that preserve supersymmetry.
(functional degrees of freedom)

Q: How does Σ depend on the deformation parameters?

A: Only a few parameters affect Σ (in 3d and 4d)

This is because almost all deformations can be realized as \mathcal{Q} -exact deformations.

$$S_0 \xrightarrow{\text{deform}} S_0 + S_1 \quad S_1 = \mathcal{Q}V + (\text{a few exceptions})$$

3d and 4d

Closet-Dumitrescu-Festuccia-Komaragodski

1309.5876

\Rightarrow Let us perform similar analysis in 5d.

- Solution to $S_{\mathcal{Q}}(\text{fermions}) = 0$
- Deformation dependence of Z

Plan

✓ Introduction

- 5d $\mathcal{N}=1$ off-shell supergravity
- Supersymmetric backgrounds
- Deformation dependence of Z
- Summary

5d $N=1$ off-shell supergravity

Zucker '99

5d $N=1$ super-Poincare algebra

Kugo-Ohashi '00

P_μ : translation (diffeomorphism)

$Q_{\alpha I}$: supersymmetry

Z : central charge $U(1)_Z$

$M_{\hat{m}\hat{n}}$: $Sp(2)_r \sim SO(5)_r$ rotation
(Euclidean)

R_a : $Sp(1)_R \sim SU(2)_R$

indices	
$\mu, \nu, \dots = 1, 2, 3, 4, 5$	global indices
$\hat{\mu}, \hat{\nu}, \dots = \hat{1}, \hat{2}, \hat{3}, \hat{4}, \hat{5}$	local indices
$\alpha, \beta, \dots = 1, 2, 3, 4$	spinor indices
$I, J, \dots = 1, 2$	$Sp(1)_R$ doublet
$a, b, \dots = 1, 2, 3$	$Sp(1)_R$ triplet

flat background

$\{Q, Q\} \sim P + Z + M + R$

curved background

Gravity (Weyl) multiplet includes "gauge fields"

for these generators.

generators $P_{\hat{\mu}}, Q_{\alpha I}, M_{\hat{\mu}\hat{\nu}}, R_{\alpha}, \Sigma$
 $SO(1,5) \times SU(2)_R \times U(1)_Z$

currents $T_{\hat{\mu}}^{\nu}, S_{\alpha I}^{\mu}, R_{\alpha}^{\mu}, J^{\mu} \in$ supercurrent multiplet

gauge fields $e_{\hat{\nu}}^{\hat{\mu}}, \psi_{I\mu\alpha}, (\omega_{\hat{\mu}\hat{\nu}}^{\hat{\rho}}), V_{\mu}^{\alpha}, Q_{\mu} \in$ Weyl multiplet.

d.o.f. $10_B \quad 32_F \quad 12_B \quad 4_B$

bosonic fermionic

$$10 + 12 + 4 = 26 \neq 32$$

Additional fields are needed.

What kinds of additional fields should we introduce?

The structure of the Weyl multiplet

can be determined from the supercurrent multiplet.

Supercurrent multiplet

$(T_{\mu\nu}^{\alpha}, S_{I\alpha}^{\mu}, R_{\alpha}^{\mu}, J^{\mu}, \dots)$ \downarrow additional operators.

Supersymmetric Yang-Mills theory

vector multiplet $(A_\mu, \lambda_{\text{Ia}}, \phi, D_a)$

SUSY tr. on the flat \mathbb{R}^5

$$S_0(\xi) A_\mu = -(\xi \gamma_\mu \lambda)$$

$$S_0(\xi) \lambda = -\cancel{F} \xi + i(\cancel{D}\phi) \xi + i D_a \tau_a \xi$$

$$S_0(\xi) \phi = i(\xi \lambda)$$

$$S_0(\xi) D_a = i(\xi \tau_a \cancel{D}\lambda) - i(\xi \tau_a [\phi, \lambda])$$

Invariant action on the flat \mathbb{R}^5

$$S_0 = \int d^5x \left(\frac{1}{4} F_{\mu\nu} F^{\mu\nu} + \frac{1}{2} D_\mu \phi D^\mu \phi - \frac{1}{2} (\lambda \cancel{D}\lambda) - \frac{1}{2} D_a D_a - \frac{1}{2} \lambda [\phi, \lambda] \right)$$

Noether current for S_0 (supersymmetry current)

$$S^\mu = -\not{\partial} \gamma^\mu \lambda + i (\not{\partial} \phi) \gamma^\mu \lambda \quad (32_F)$$

E-M tensor

$$T^{\mu\nu} = F^\mu{}_\rho F^{\nu\rho} - \frac{1}{4} g^{\mu\nu} F_{\rho\sigma} F^{\rho\sigma} + \dots \quad (10_B)$$

SU(2)_R current

$$R_a^\mu = \frac{1}{2} (\lambda \tau_a \gamma^\mu \lambda) \quad (12_B)$$

U(1)_Z current

$$J^\mu = \frac{1}{4} \epsilon^{\mu\kappa\lambda\rho} F_{\kappa\lambda} F_{\rho\sigma} - 2i \partial_\nu (F^{\mu\nu} \phi) \quad (4_B)$$

These operators does not form a closed rep of S_0 .

repetition of

$$\left\{ \begin{array}{l} M_{\rho\sigma} = i F_{\rho\sigma} \phi + \frac{1}{8} (\lambda \gamma_{\rho\sigma} \lambda) \quad (10_B) \end{array} \right.$$

S_0 gives

$$\left\{ \begin{array}{l} \Phi = \frac{1}{2} \phi^2 \quad (1_B) \end{array} \right.$$

$$\left\{ \begin{array}{l} \chi_I = i \lambda_I \phi \quad (8_F) \end{array} \right.$$

$$\left\{ \begin{array}{l} X_a = \frac{1}{2} (\lambda \tau_a \lambda) \quad (3_B) \end{array} \right.$$

We obtained supercurrent multiplet with $40_B + 40_F$ d.o.f.

$(T_{\nu}^{\mu}, S_{Ia}^{\mu}, R_a^{\mu}, J^{\mu}, M_{\mu\nu}, \Phi, \chi_{Ia}, \chi_a)$
conserved currents additional operators

Weyl multiplet with $40_B + 40_F$ d.o.f.

$(e_{\mu}^{\nu}, \psi_{\mu Ia}, V_{\mu}^a, a_{\mu}, \omega^{\mu\nu}, C, \eta_{Ia}, t_a)$
gauge fields additional fields

additional fields $14_B + 8_F$

$\psi_{\mu\nu}$ anti-sym tensor	10_B
t_a triplet scalars	3_B
η_{Ia} fermion	8_F
C singlet scalar	1_B

Matter action in a weakly curved background

$$S = S_0 + S_1$$

flat small deformation

\mathcal{L} linear in the Weyl mult.

$$S_1 = \int d^5x \left[-\Delta e_{\mu}^{\nu} T_{\nu}^{\mu} + \Delta \gamma_{\mu} S^{\mu} - \Delta V_{\mu}^{\alpha} R_{\alpha}^{\mu} - \Delta a_{\mu} J^{\mu} + \dots \right]$$

For the following analysis we need the full
(non-linear) action

Construction is tedious.

Fortunately it is given in

Kugo-Ohashi { hep-ph/0006231

hep-ph/0010288

Supersymmetric backgrounds

Once a background Weyl multiplet is given we can give the susy action of matter fields on the background.

For the existence of rigid susy $S_0(\xi)$, the background must satisfy

$$S_0(\xi) \text{ (fermions)} = 0$$

There are two fermions $\psi_{\alpha I}$ and $\eta_{\alpha I}$ in the Weyl mult. We should consider two conditions.

Susy backgrounds are defined by

$$\begin{cases} \delta_{\alpha}(\xi) \psi_{\mu} = 0 & \text{Killing spinor } \xi. \\ \delta_{\alpha}(\xi) \eta = 0 & \text{Auxiliary } \xi. \end{cases}$$

Susy tr.

$$\delta_{\alpha}(\xi) \psi_{\mu} = D_{\mu} \xi - f_{\mu\nu} \gamma^{\nu} \xi + \frac{1}{4} \gamma_{\mu\rho\sigma} \nu^{\rho\sigma} \xi - \tau \gamma_{\mu} \xi$$

$$\begin{aligned} \delta_{\alpha}(\xi) \eta = & -2\gamma_{\nu} \xi D_{\mu} \nu^{\mu\nu} + \xi C + 4(\not{\mathcal{D}} \tau) \xi \\ & + 8(\not{\mathcal{F}} - \not{\mathcal{D}}) \tau \xi + \gamma^{\mu\nu\rho\sigma} \xi f_{\mu\nu} f_{\rho\sigma} \end{aligned}$$

$$(f_{\mu\nu} = \partial_{\mu} a_{\nu} - \partial_{\nu} a_{\mu} : U(1) \text{ z field strength})$$

Comment on the parameter ξ

Lorenzian case : $\xi \sim \xi^*$ (symplectic Majorana)

Euclidean case : ξ, ξ^* independent.

Although we consider Euclidean case,
we impose the symplectic Majorana condition

$$\xi_{\alpha I} = J_{\alpha\beta} \epsilon_{IJ} (\xi_{\beta J})^*$$

just for simplicity.

((2,4) of $SU(2)_R \times SO(5) = Sp(1)_R \times Sp(2)$ is real)

non-vanishing bi-linears

$$S = (\xi \xi), \quad R^\mu = (\xi \gamma^\mu \xi), \quad T_{\mu\nu}^a = \frac{1}{S} (\xi T_a \gamma_{\mu\nu} \xi)$$

ξ is real and nowhere vanishing $\rightarrow S > 0$

Fierz identity $\rightarrow R^\mu R_\mu = S^2 > 0$

\rightarrow R^μ define a foliation

We can locally define x^5 by

$$R^\mu \partial_\mu = \partial_5$$

and take the local frame such that

$$e_{\hat{m}} = e_{\hat{n}} dx^n, \quad e_{\hat{5}} = S(dx^5 + V_m dx^m)$$

$$\left(\begin{array}{l} m, n = 1, 2, 3, 4 \\ \hat{m}, \hat{n} = \hat{1}, \hat{2}, \hat{3}, \hat{4} \end{array} \right) \quad ds^2 = g_{mn} dx^m dx^n + S^2 (dx^5 + V_m dx^m)^2$$

$e_{\hat{n}}, S, V_m$ may depend on x^5

Tangent space is divided into

{ horizontal space $\hat{M} = \{1, 2, 3, 4\}$
vertical space \hat{E}

$\rightarrow J_{\mu\nu}^a R^\nu = 0 \Rightarrow J_{\mu\nu}^a$ are essentially 4d tensors

Fierz in the horizontal space

$\hookrightarrow -\frac{1}{2} \epsilon_{\mu\nu} \chi^{\rho\sigma} R_\lambda J_{\rho\sigma}^a = 0 \Rightarrow J_{\mu\nu}^a$ are anti-self-dual
in the horizontal space

$J_{\mu\nu}^a$ enjoy the quaternion algebra

Fierz $\rightarrow J_{\hat{m}\hat{n}}^a J_{\hat{p}\hat{q}}^b = \delta_{ab} \delta_{\hat{m}\hat{n}} + i \epsilon_{abc} J_{\hat{m}\hat{n}}^c$

$\hookrightarrow \gamma_\mu \xi^{\hat{M}} = \xi^{\hat{S}} \Rightarrow \gamma_{\hat{S}} \xi^{\hat{S}} = \xi^{\hat{S}}$

$\xi^{\hat{S}}$ has positive chirality

γ -matrices

$$\gamma^{\uparrow, \hat{2}, \hat{3}} = \begin{pmatrix} & -i\tau_{1,2,3} \\ i\tau_{1,2,3} & \end{pmatrix} \quad \gamma^{\hat{4}} = \begin{pmatrix} & \mathbb{1} \\ \mathbb{1} & \end{pmatrix} \quad \gamma^{\hat{5}} = \begin{pmatrix} \mathbb{1} & \\ & -\mathbb{1} \end{pmatrix}$$

With this convention we can take a gauge with

$$\underbrace{\zeta}_{\leftarrow} \alpha \begin{pmatrix} \mathbb{1}_2 \\ 0 \end{pmatrix} \Bigg|_{\uparrow}^{\leftarrow} \text{ by } Sp(2)_L \times Sp(1)_R \text{ rotation.}$$

$(\zeta \in (4, 2))$

We can span the spinor space by the basis

$$\underbrace{\gamma^{\hat{5}} \zeta = \zeta \alpha \begin{pmatrix} \mathbb{1}_2 \\ 0 \end{pmatrix}, \gamma^{\uparrow, \hat{2}, \hat{3}} \zeta \alpha \begin{pmatrix} 0 \\ i\tau_{1,2,3} \end{pmatrix}, \gamma^{\hat{4}} \zeta \alpha \begin{pmatrix} 0 \\ \mathbb{1}_2 \end{pmatrix}, \zeta \tau_a = \begin{pmatrix} \tau_a \\ 0 \end{pmatrix}}_{\gamma^{\hat{\mu}} \zeta} \quad \underbrace{\zeta \tau_a}_{\zeta \tau_a}$$

ζ

Killing spinor eq

Pan (1308.1567)

Y.I-Matsuno (1404.0210)

$$S_{\alpha}(\xi)\gamma_{\mu} = D_{\mu}\xi - f_{\mu\nu}\gamma^{\nu}\xi + \frac{1}{4}\gamma_{\mu\rho\sigma}\gamma^{\rho\sigma}\xi - t\gamma_{\mu}\xi = 0$$

By using the spinor basis we decompose this into

$$\xi\gamma_{\mu}S_{\alpha}(\xi)\gamma_{\nu} = 0 \quad -\textcircled{1}$$

$$\xi^{\top}\epsilon_{\alpha}S_{\alpha}(\xi)\gamma_{\mu} = 0 \quad -\textcircled{2}$$

①

$$0 = (\xi \gamma_{\hat{\alpha}} \delta_{\alpha} \gamma_{\hat{\alpha}}) \\ = \frac{1}{2} D_{\hat{\alpha}} R_{\hat{\alpha}} - S f_{\hat{\alpha}\hat{\alpha}} - \frac{S}{4} \epsilon_{\hat{\alpha}\mu\nu\rho\sigma} \gamma_{\hat{\alpha}} \gamma^{\mu} \gamma^{\nu} \gamma^{\rho} \gamma^{\sigma} + S t_{\hat{\alpha}} J_{\hat{\alpha}}^a$$

Symmetric part

$$D_{\mu} R_{\lambda} + D_{\lambda} R_{\mu} = 0$$

$\Rightarrow R^{\mu}$ is a Killing vector

The background vielbein

$$e_{\hat{m}}^{\mu} = e_n^{\hat{m}} dx^n, \quad e_{\hat{5}}^5 = S(dx^5 + V_m dx^m)$$

$e_n^{\hat{m}}$, S , V_m depend on x^m only.

independent of x^5

①

$$0 = (\xi \gamma_{\hat{\alpha}} \delta_{\alpha} \psi_{\hat{\alpha}}) \\ = \frac{1}{2} D_{\hat{\mu}} R_{\hat{\alpha}} - S f_{\hat{\mu}\hat{\alpha}} - \frac{S}{4} \epsilon_{\hat{\mu}\nu\rho\sigma} \gamma_{\rho\sigma} \psi_{\hat{\alpha}} + S t_{\hat{\alpha}} J_{\hat{\mu}\hat{\alpha}}^a$$

$(\hat{\lambda}, \hat{\mu}) = (5, m)$ components

$$f_{m5} = \frac{1}{2} \partial_m S \quad \left(\begin{array}{l} f_{\mu\nu} = \partial_{\mu} a_{\nu} - \partial_{\nu} a_{\mu} \\ U(1)_2 \text{ field strength} \end{array} \right)$$

This can be locally solved by

$$a = a_m dx^m + \frac{1}{2} S dx^5 \quad (\text{up to } U(1)_2 \text{ gauge tr.})$$

with $a_m(x^m)$ independent of x^5

①

$$0 = (\xi \gamma_{\hat{\alpha}} \delta_{\alpha} \psi_{\hat{\alpha}}) \\ = \frac{1}{2} D_{\hat{\mu}} R_{\hat{\alpha}} - S f_{\hat{\mu}\hat{\alpha}} - \frac{S}{4} \epsilon_{\hat{\mu}\hat{\nu}\hat{\rho}\hat{\sigma}} \gamma^{\hat{\rho}\hat{\sigma}} + S t_a J_{\hat{\mu}\hat{\alpha}}^a$$

anti-sym part of the horizontal part $(\hat{\mu}, \hat{\alpha}) = (\hat{\rho}, \hat{\sigma})$
 can be solved by

$$\gamma^{\hat{\rho}\hat{\sigma}} = \epsilon_{\hat{\rho}\hat{\mu}\hat{\nu}\hat{\alpha}} \left(\frac{S}{4} V_{\hat{\mu}\hat{\nu}}^{\hat{\alpha}} - f_{\hat{\mu}\hat{\nu}}^{\hat{\alpha}} + t_a J_{\hat{\mu}\hat{\nu}}^a \right) \\ (V_{\hat{m}\hat{n}} = \partial_{\hat{m}} V_{\hat{n}} - \partial_{\hat{n}} V_{\hat{m}})$$

②

$$\xi^\dagger T_a S_\alpha(\xi) \psi_\mu = 0$$

$$\begin{aligned} S_\alpha(\xi) \psi_\mu &= D_\mu \xi + \dots \\ &= \partial_\mu \xi + \frac{1}{4} \omega_{\mu\nu\alpha} \hat{\gamma}^{\nu\alpha} \xi - V_\mu^a T_a \xi + \dots \end{aligned}$$

We can use ② to give the $SU(2)_R$ gauge field

$$V_\mu^a = \frac{1}{4} \omega_{\mu\nu\alpha} J_{\nu\alpha}^a + \frac{1}{4} J_{\mu\alpha}^a \psi^\nu \hat{\gamma}^{\nu\alpha} - T_a$$

$$V_\mu^a = \frac{1}{4} \omega_{\mu\nu\alpha} J_{\nu\alpha}^a + \frac{1}{2} J_{\mu\alpha}^a \psi^\nu \hat{\gamma}^{\nu\alpha}$$

Solution to the Killing spinor eq. $S\psi_\mu = 0$.

vielbein

$e_\mu^{\hat{\nu}}$

$e_{\hat{m}}^{\hat{\nu}}, V_m, S$

$U(1)_2$ gauge field

A_μ

A_m, A_5

anti-sym tensor

$\eta_{\mu\nu}$

$\eta_{\hat{m}\hat{n}}, \eta_{\hat{m}\hat{5}}$

$Sp(1)_R$ triplet

T_a

T_a

$Sp(1)_R$ gauge field

V_μ^a

V_m^a, V_5^a

singlet scalar

C

C

red : written in terms of other fields

green : independent of x_5

blue : unfixed

Auxiliary eq.

Y. I. Matsuno (1404.0210)

$$0 = S_2 \left(\frac{3}{2} \right) \eta = -2 \gamma_\nu \xi D_\mu \gamma^{\mu\nu} + \frac{3}{2} C + 4(\not{D} \not{t}) \frac{3}{2} \\ + 8(\not{f} - \not{g}) t \frac{3}{2} + \gamma^{\mu\nu\rho\sigma} \frac{3}{2} f_{\mu\nu} f_{\rho\sigma}$$

With the spinor basis we decompose this into

$$0 = S^{-1} \left(\frac{3}{2} S_2 \eta \right) - \textcircled{3}$$

$$0 = S^{-1} \left(\frac{3}{2} \gamma_m S_2 \eta \right) - \textcircled{4}$$

$$0 = S^{-1} \left(\frac{3}{2} \tau_a S_2 \eta \right) - \textcircled{5}$$

③

$$\begin{aligned} 0 &= S^{-1}(3\delta\epsilon^{\eta}) \\ &= -2D_{\mu}\eta^{\mu\hat{E}} + C + 4T_a J_{m\hat{n}}^a (f_{m\hat{n}}^{\hat{n}} - g_{m\hat{n}}) + \epsilon_{mnp}^{(a)} f_{m\hat{n}}^{\hat{n}} f_{p\hat{s}}^{\hat{s}} \end{aligned}$$

This can be used to determine C

$$C = 2D_{\mu}\eta^{\mu\hat{E}} - 4T_a J_{m\hat{n}}^a (f_{m\hat{n}}^{\hat{n}} - g_{m\hat{n}}) - \epsilon_{mnp}^{(a)} f_{m\hat{n}}^{\hat{n}} f_{p\hat{s}}^{\hat{s}}$$

By using relations we have obtained the remaining equations (4) and (5) are drastically simplified.

$$(4) \quad 0 = S^{-1} \left(\frac{3}{5} \sigma_m \delta a \eta \right) = 2S^{-1} \partial_5 \nu_{m5}$$

$$(5) \quad 0 = S^{-1} \left(\frac{3}{5} \tau_a \delta a \eta \right) = 4S^{-1} \partial_5 t_a$$

$\Rightarrow \nu_{m5}$ and t_a are independent of x^5

We have completely solved $\delta a \eta = \delta a \eta = 0$.

The solution of $S_{\alpha\gamma\mu} = S_{\alpha\eta} \eta = 0$

vielbein	\hat{e}_{μ}^{ν}
$U(1)_2$ gauge field	A_{μ}
anti-sym tensor	$\eta_{\mu\nu}$
$Sp(1)_R$ triplet	t_a
$Sp(1)_R$ gauge field	V_{μ}^a
singlet scalar	C

$\hat{e}_{\mu}^{\nu}, V_{\mu}, S$
A_{μ}, A_5
$\eta_{\mu\nu}, \eta_{\mu\nu}^5$
t_a
V_{μ}^a, V_5^a
C

red : written in terms of other fields

green : independent of x^5

All fields are independent of x^5 .

The general solution

$$\sum_{\alpha} I = \sqrt{\frac{S}{2}} \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$t_a = (\text{indep})$$

$$e_{\hat{n}}^{\hat{m}} = (\text{indep})$$

$$V_{\hat{m}}^a = \frac{1}{4} \omega_{\hat{m}\hat{p}\hat{q}}^{(4)} J_{\hat{p}\hat{q}}^a + \frac{1}{2} J_{\hat{m}\hat{p}}^a \gamma_{\hat{p}\hat{q}}$$

$$V_{\hat{q}}^a = \frac{1}{2} J_{\hat{m}\hat{n}}^a (f_{\hat{m}\hat{n}} - \frac{S}{2} V_{\hat{m}\hat{n}}) + t_a$$

$$C = 2 D_{\hat{m}}^{(a)} \gamma_{\hat{m}\hat{q}}^a + 4 t_a J_{\hat{m}\hat{n}}^a f_{\hat{m}\hat{n}} + 32 t_a t_a$$

$$e_{\hat{q}}^{\hat{p}} = S = (\text{indep})$$

$$- \epsilon_{\hat{m}\hat{p}\hat{q}}^{(4)} (f_{\hat{m}\hat{n}} - \frac{S}{2} V_{\hat{m}\hat{n}}) (f_{\hat{p}\hat{q}} - \frac{S}{2} V_{\hat{p}\hat{q}})$$

$$a_{\hat{m}} = (\text{indep})$$

$$a_S = \frac{1}{2} S$$

$$\gamma_{\hat{p}\hat{q}}^a = \epsilon_{\hat{p}\hat{q}\hat{m}\hat{n}}^{(4)} \left(\frac{S}{4} V_{\hat{m}\hat{n}}^a - f_{\hat{m}\hat{n}}^a + t_a J_{\hat{m}\hat{n}}^a \right)$$

$$V_{\hat{m}\hat{q}}^a = (\text{indep})$$

The isometry

The existence of the isometry is expected from the commutation relation

$$\{S_0(\xi_1), S_0(\xi_2)\} = \underline{S_{\text{diff}}} + S_{U(1)_2} + S_{U(1)_R} + S_{SO(5)_V}$$

The parameter for S_{diff} is $\sim \xi_1 \gamma^\mu \xi_2$

Existence of rigid SUSY $S_0(\xi)$

→ Existence of isometry $S_{\text{diff}}(R^n)$

In the gauge that we have chosen,

$$(S_0(\xi))^2 = \partial_5$$

Remark

We have not considered global issues.

A single coordinate patch has been focused on.



future work

Deformation dependence of Z

Let S_0 be a theory of matter fields defined on a susy background.

(example)

$$S_0 = \int d^5x \sqrt{g} \left(\frac{1}{4} g_{\mu\nu} g_{\rho\sigma} F_{\mu\nu} F_{\rho\sigma} + \dots \right)$$

A small deformation of the background

$$S_0 \rightarrow S_0 + S_1$$

$$S_1 = \int d^5x \sqrt{g} \left[-\Delta e_{\nu}^{\mu} T_{\mu}^{\nu} + \Delta \psi_{\mu} S^{\mu} + \dots \right]$$

If S_1 is $\mathcal{S}(\mathfrak{Z})$ exact, this deformation does not affect the partition function Z .

Question

To what extent can we realize susy preserving deformations by adding Q-exact terms to the action?

We follow the following steps.

① determine S_0 -transf. of the ^{fermionic} currents S^{μ} and χ .
in the curved background

② compute general S_0 -exact action of the form

$$S_{\text{exact}} = \int d^5x \sqrt{g} (F_{\mu}^{\text{I}\alpha} S^{\mu} + F^{\text{I}\alpha} \chi_{\text{I}\alpha})$$

③ compare this with general susy preserving deformation.

① Determination of $S_0 S^M$ and $S_0 \chi$

We assume the background is S_0 invariant



A small deformation ($\Delta e_{\mu\nu}^{\hat{a}}$, $\Delta \gamma_{\mu\nu}$, ...) are linearly transformed. ($S_0 e_{\mu\nu}^{\hat{a}}$ etc. are in the literature)



We can determine S_0 (currents) so that

S_1 is susy invariant.

Example

Focus on the terms in $S_0 S_1$ containing $\Delta \eta \equiv \eta$

$$\begin{aligned} \delta_0 S_1 &= \delta_0 \int \dots + \underbrace{\Delta V_\mu^a}_{\downarrow \delta_0} R_a^\mu + \underbrace{\Delta \eta^\mu}_{\downarrow \delta_0} + \dots \\ &= \int \dots - \frac{1}{4} (\xi \tau_a \gamma_\mu \eta) R_a^\mu + \eta \delta_0 \chi + \dots \end{aligned}$$

For this to vanish

$$\eta \delta_0 \chi - \frac{1}{4} (\eta \tau_a \gamma_\mu \xi) R_a^\mu + \dots = 0$$

$$\begin{aligned} \Rightarrow \delta_0 \chi &= \frac{1}{4} \tau_a \gamma_\mu \xi R_a^\mu + \frac{1}{4} \tau_a \xi \chi_a - \frac{1}{2} \gamma_{\mu\nu} \xi \rho^{\mu\nu} \\ &\quad + \gamma^\mu \xi D_\mu \Phi + f_{\mu\nu} \gamma^{\mu\nu} \xi \Phi + 16 t \xi \Phi. \end{aligned}$$

② So exact terms

$$S_{\text{exact}} = \int \mathcal{L} d^5x (F, \chi) \quad F: \text{5 indep. spinor func.} \\ (\text{bosonic})$$

expansion of F by the spinor basis

$$F \rightarrow f_{\alpha}, f^{\alpha}, \tau_{\alpha\beta}, f^{\hat{m}} \gamma_{\hat{m}}^{\alpha}$$

$$(F, \chi) = f(\chi) + \frac{4}{5} f^{\alpha}(\chi \tau_{\alpha}) - \frac{2}{5} f^{\hat{m}}(\chi \gamma_{\hat{m}})$$

The second term gives \downarrow

$$S_{\text{exact}} = \int d^5x \mathcal{L} \frac{4}{5} f^{\alpha}(\chi \tau_{\alpha})$$

(continued)

$$= \int d^5x \sqrt{g} \left(f^a R_a^{\hat{S}} + f^a X_a - 2f^a J_{mn}^a M^{\hat{m}\hat{n}} + 4f^a J_{mn}^a f^{\hat{m}\hat{n}} \Phi + 64f^a T_a \right)$$

$\Delta V_{\hat{S}}^a R_a^{\hat{S}} \quad \Delta T_a X_a \quad \dots$

③ Comparison to $S_1 = \int \sqrt{g} (-\Delta e_{\hat{r}}^{\hat{\nu}} T_{\hat{\nu}}^{\hat{r}} + \dots)$

We can read off the corresponding background deformation

$$\left\{ \begin{array}{l} \Delta V_{\hat{S}}^a = f^a \\ \Delta T_a = f_a \\ \Delta J_{mn}^a = -2f^a J_{mn}^a \\ \Delta C = 4f^a J_{mn}^a f^{\hat{m}\hat{n}} + 64f^a T_a \\ \Delta e_{\hat{r}}^{\hat{\nu}} = \Delta a_{\hat{r}} = \Delta J_{mn}^a = \Delta V_{\hat{m}}^a = 0 \end{array} \right.$$

The general solution

$$\mathbb{Z}^n \mathbb{I} = \sqrt{\frac{5}{2}} \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$t_a = (\text{indep})$$

$$e_{\hat{n}} = (\text{indep})$$

$$V_{\hat{n}}^a = \frac{1}{4} \omega_{mnpq}^{(4)} J_{pq}^a + \frac{1}{2} J_{mp}^a \nu_{pq}$$

$$V_{\hat{5}}^a = \frac{1}{2} J_{mn}^a \left(f_{mn} - \frac{5}{2} V_{mn} \right) + t_a$$

$$C = 2 D_{\hat{m}}^{(4)} \nu_{\hat{m}\hat{5}} + 4 t_a J_{\hat{m}\hat{n}}^a f_{mn} + 32 t_a t_a$$

$$- \epsilon_{mnpq}^{(4)} \left(f_{mn} - \frac{5}{2} V_{mn} \right) \left(f_{pq} - \frac{5}{2} V_{pq} \right)$$

$$e_{\hat{5}} = S = (\text{indep})$$

$$a_{\hat{m}} = (\text{indep})$$

$$a_5 = \frac{1}{2} S$$

$$\nu_{pq}^a = \epsilon_{pqmn}^{(4)} \left(\frac{5}{4} V_{mn}^a - f_{mn}^a + t_a J_{mn}^a \right)$$

$$\nu_{\hat{m}\hat{5}} = (\text{indep})$$

This is generated by the change of the independent field t^a .

$$\Delta t^a = f^a$$

We can freely change t^a by Q-exact def.

t^a does not affect Σ (at least locally).

Other terms in $\delta \int F_X$ are also computed similarly

A exact terms in $\delta \int F_n S^n$ are more complicated.

Let us find a shortcut.

We followed the following steps.

① consider the small deformation

$$S_1 = \int \Delta A_i^B J_i^B + \Delta A_i^F J_i^F$$

where $(A_i^B, A_i^F) \dots$ gravity multiplet

$(J_i^B, J_i^F) \dots$ current multiplet

② Susy transf. of ΔA_i^B are linear in $\Delta A_i^F \equiv A_i^F$

$$S_a \Delta A_i^B = \Delta A_j^F M_{ji}$$

From the SUSY invariance of S_1

$$0 = S_a S_1 = \int \underbrace{S_a \Delta A_i^B J_i^B}_{\parallel} - \Delta A_i^F S_a J_i^F$$

we obtain

$$S_a J_i^F = M_{ij} J_i^B$$

③ general Q -exact deformation

$$S_0 \int f_i J_i^F = \int f_i S_0 J_i^F = \int f_i M_{ij} J_j^B$$

By comparing this to $S_1 = \int \Delta A_i J_i^B$
we can read off

$$\begin{aligned} \Delta A_i^B (Q\text{-exact}) &= f_i M_{ij} \\ &= S_0 \Delta A_i^B \end{aligned} \quad \Bigg| \quad \begin{array}{l} A_i^F \rightarrow f_i \\ A_i^F \rightarrow f_i \end{array}$$

~ Shortcut ~

Q -exact def. can be obtained
from susy trans. by the replacement

$A_i^F \rightarrow f_i$
fermions parameters.

Susy transf of bosonic components in Weyl.

$$\delta_{\alpha} e_{\mu}^{\hat{\nu}} = -2(\xi \hat{g}^{\nu} \chi_{\mu})$$

$$\delta_{\alpha} a_{\mu} = -(\xi \chi_{\mu})$$

$$\begin{aligned} \delta_{\alpha} V_{\mu}^{\alpha} = & -\frac{1}{4}(\xi T_{\alpha} \gamma_{\mu} \eta) + (\xi T_{\alpha} \gamma^{\lambda} R_{\lambda \mu}(\alpha)) + (\xi T_{\alpha} \gamma^{\lambda \sigma} f_{\rho} \chi_{\mu}) \\ & - (\xi T_{\alpha} \gamma^{\lambda \sigma} \nu_{\rho} \chi_{\mu}) + 6(\xi \chi_{\mu}) T_{\alpha} \end{aligned}$$

$$\delta_{\alpha} T_{\alpha} = -\frac{1}{4}(\xi T_{\alpha} \eta),$$

$$\delta_{\alpha} \mathcal{V}_{\mu\nu} = \frac{1}{2}(\xi \gamma_{\mu\rho\sigma} R^{\rho\sigma}(\alpha)) + \frac{1}{2}(\xi \gamma_{\mu\nu} \eta)$$

$$\delta_{\alpha} c = -(\xi \hat{\Delta} \eta) - 11(\xi t \eta) - \frac{3}{4}(\xi \gamma_{\mu\nu} \nu^{\mu\nu} \eta) - 4(\xi t \gamma^{\mu\nu} R_{\mu\nu}(\alpha))$$

By the replacement $(\eta, \chi_{\mu}) \rightarrow (-\frac{5}{4} f_a T_a \xi, 0)$

We reproduce the background deformation corresponding to

$$S_{\text{exact}} = \delta_{\alpha} \int d^5x \sqrt{g} \frac{4}{5} f^a (\xi T_a \chi)$$

With this prescription, we can realize all the susy-pres,
deformations as \mathcal{Q} -exact deformations.

Comments

- We have not taken care of global issues.
- We can only claim that "local" degrees of freedom do not affect \mathcal{Z} .

- In some examples (S^5 , $S^4 \times S^1$, etc.) \mathcal{Z} depends on a few parameters.

- Similar analysis can be done for background vector multiplets.

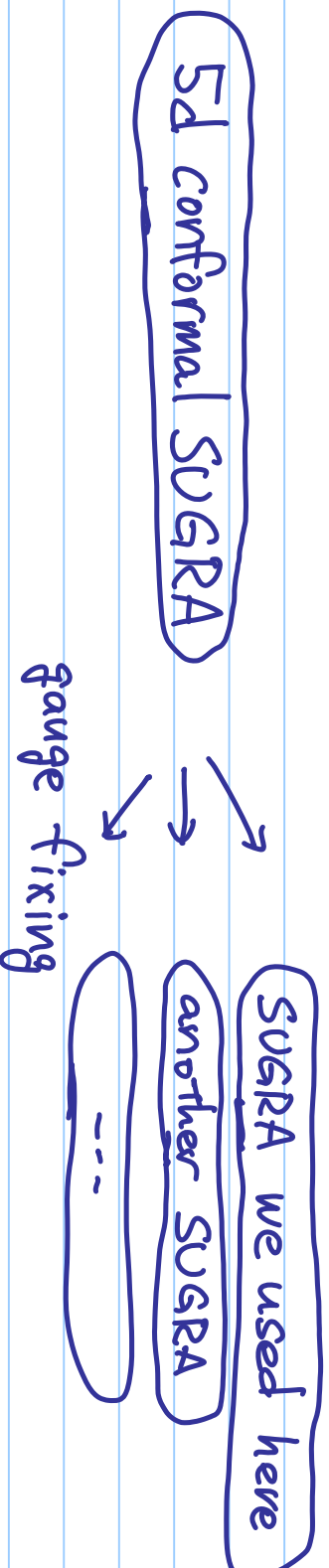
Summary

- In the framework of 5d $\mathcal{N}=1$ supergravity we constructed Susy-pres. background.
- We took Euclidean signature, and imposed symplectic Majorana cond. on \mathbb{S}^3 just for simplicity.
- As long as we focus on a single coordinate patch susy-pres. deformations can be realized as \mathbb{Q} -exact deformations.

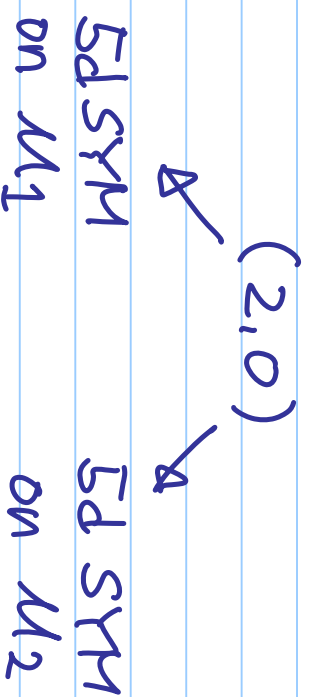
Future directions.

- Removing the restriction on \mathbb{Z}
 - Complex \mathbb{Z} ,
 - Lorenzian signature
- Global issues
 - How many parameters can affect \mathbb{Z} for a given topology?
- reduction to 4d
 - With the isometry we can reduce the sol, to 4d. (straight forward?)

o Other off-shell SUGRA,



o Two 5d solutions from the same 6d sol.



It is easy to construct a pair (M_1, M_2)

$$Z(M_1) \stackrel{?}{=} Z(M_2)$$

Thank You!